

# MATHEMATICAL SIMULATIONS IN 3D ANIMATION



GINA BERNARDINI

# OVERVIEW

- What are simulations in animation?
- Why are they useful?
- Character simulation:  
Clothing and hair
- Creating a simple  
interactive 3D curtain

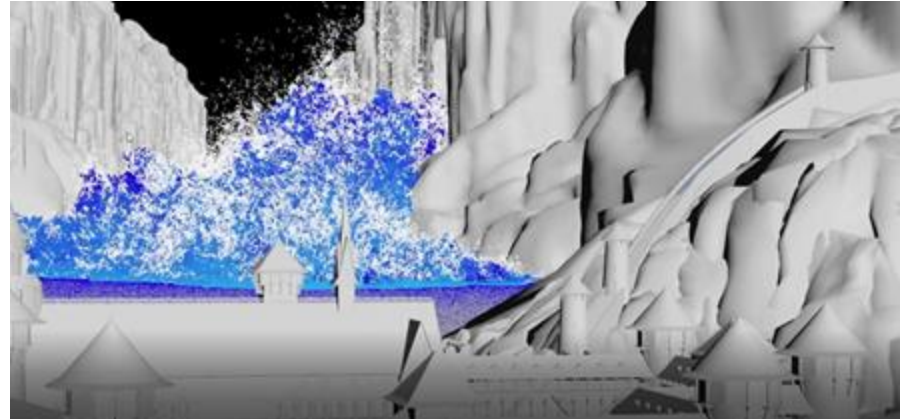
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# SIMULATIONS IN 3D ANIMATION

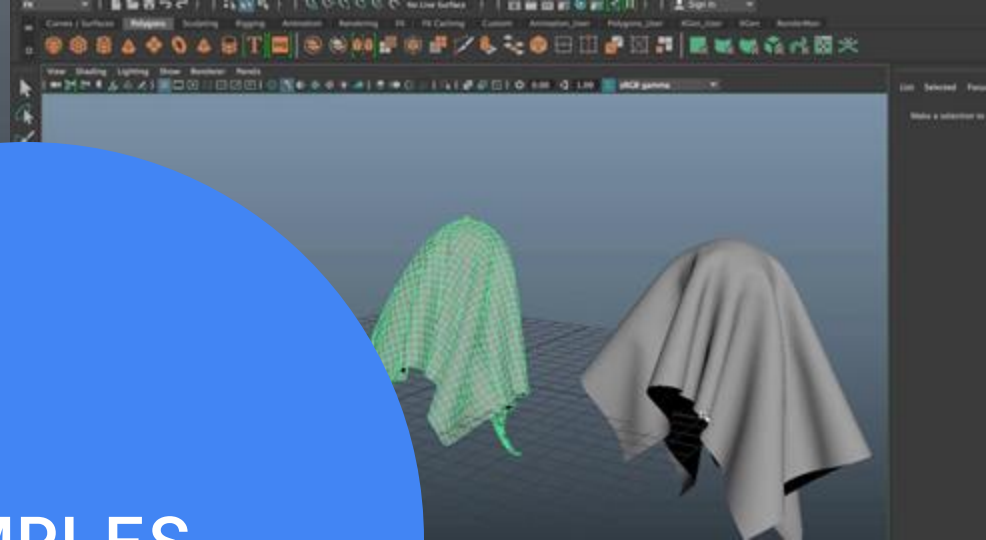
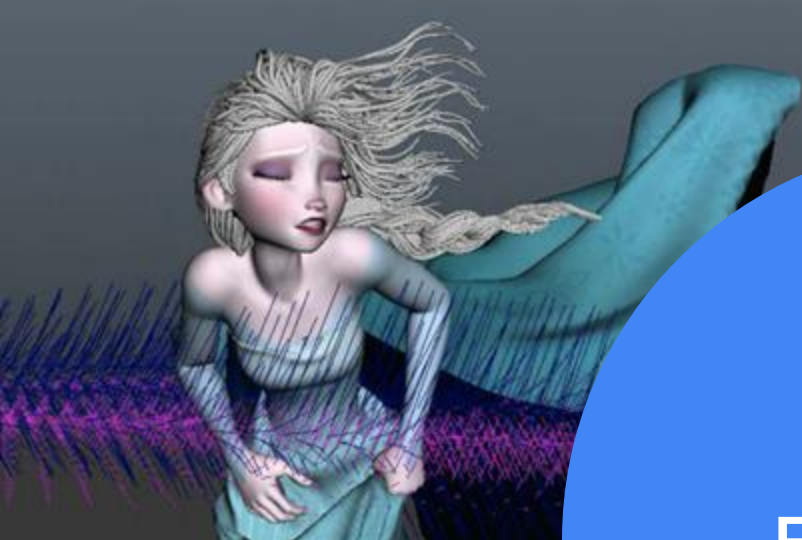


# CATEGORIES OF SIMULATION

- PARTICLE SYSTEM SFX
  - WATER, SMOKE, FIRE, WIND, ETC.
- CHARACTER EFFECTS
  - CLOTHING, HAIR
- LIGHTING AND SHADING
- CROWDS + COMBINATORICS





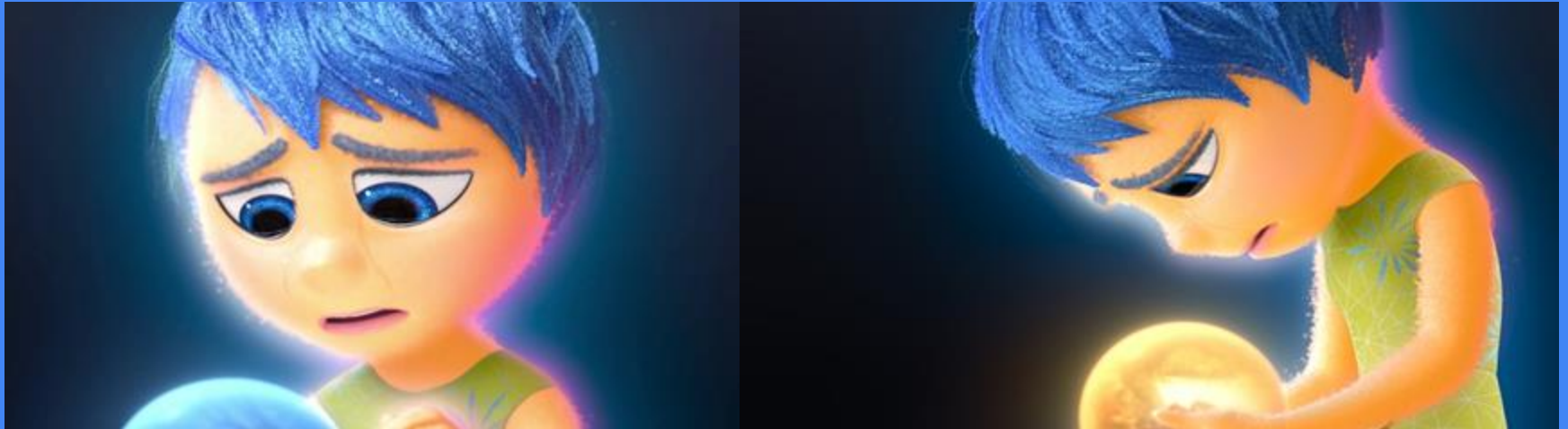


# EXAMPLES



# WHAT KIND OF MATH GOES INTO SIMULATIONS?

- A LOT!
  - Math is employed in many different ways with simulations. Today I will primarily be discussing: algebra, geometry, discrete



# WHERE IS THE MATH?

- Communicate to the computer and software how to generate and apply the motion to objects, particles, etc.

```
321 - var initialiseArrays = function() {  
322     x = new Array(N);           // Positions  
323     y = new Array(N);  
324     vx = new Array(N);         // Velocities  
325     vy = new Array(N);  
326     vhx = new Array(N);        // Half step velocities  
327     vhy = new Array(N);  
328     ax = new Array(N);         // Accelerations  
329     ay = new Array(N);  
330     rho = new Array(N);        // Densities  
331 };  
332  
333 - var randomInit = function() {  
334 -     for (i = N; i--;) {  
335         // Initialize particle positions  
336         x[i] = random(h, 0.25);  
337         y[i] = random(0.5, 0.95);  
338  
339         // Initialize particle velocities  
340         vx[i] = random(-0.02, 0.02);
```

- Create equations to represent the environment that you are trying to create.
- Everything in 3D environments are created by the programmer, including elements like gravity. You do not need to follow conventional laws of physics.

# WHERE IS THE MATH?

- Topologies of the models. These simulations are applied onto vertices of objects, therefore we must consider the geometric relationships between them.

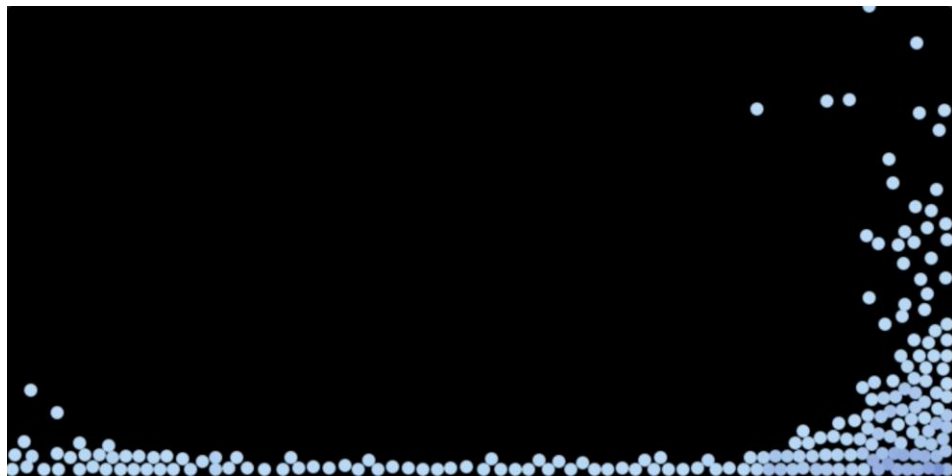


- Computer is constantly computing and storing the positions and other attributes of these particles when executing simulations. Takes a lot of power.



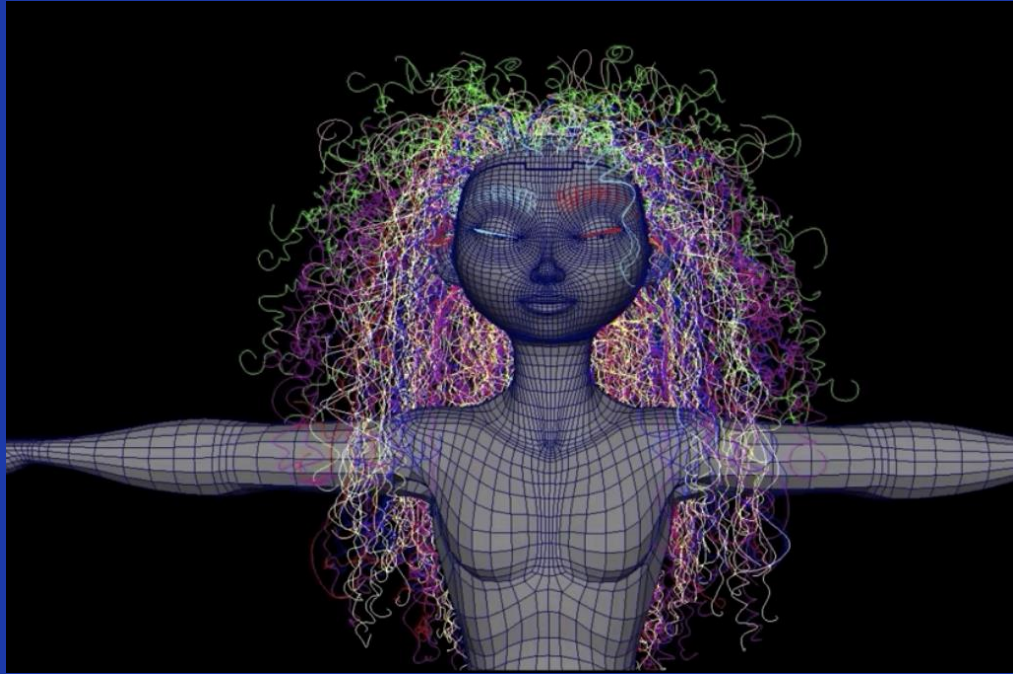
# WHY DO WE USE SIMULATIONS?

- Efficiency
  - In 2D animation, we would have to hand draw each of these effects.
  - Combinatorics- helps with crowds and prevents character modelers from having to create hundreds of different characters. Simulations apply different colors, hairstyles, clothes, etc. randomly.
- Realism
  - Realistically emulate the motions of nature.
  - Can integrate with live action film.
- Exaggeration and Appeal
  - Effective for entertainment purposes. Can create cartoony effects.



<https://www.khanacademy.org/computer-programming/spin-off-of-smoothed-particle-hydrodynamics/4661787965652992>

# CHARACTER EFFECTS



- Different because they also have to follow the mesh of the character
- Often need to be exaggerated or have their own environment for appeal purposes









# CURLY HAIR SIMPLE SIMULATION

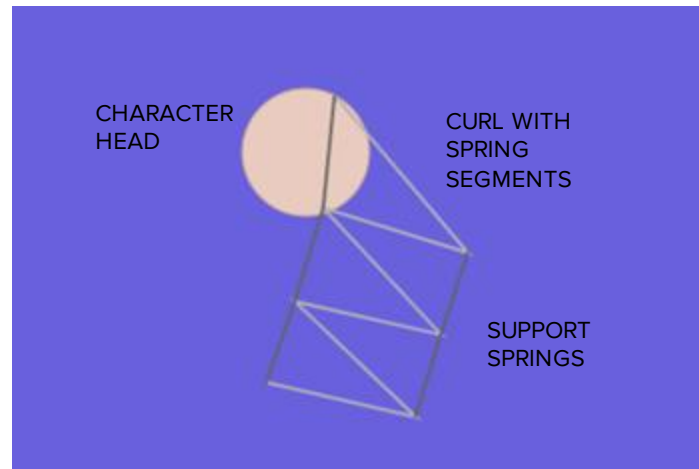
- Break down into simple components

- Instead of using one long hair, each piece is broken down into segments - chains of springs
- Had to invent additional support springs to simulate what real hair does. Must be INVENTIVE!

- Spring-mass system

- Turns out to be simple spring mass system.
- In a real production, you would then play with the variables to get the desired look and assign attributes to make it look like hair.

<https://www.khanacademy.org/computing/pixar/simulation/hair-simulation-101/a/mass-spring-system-with-support-springs>

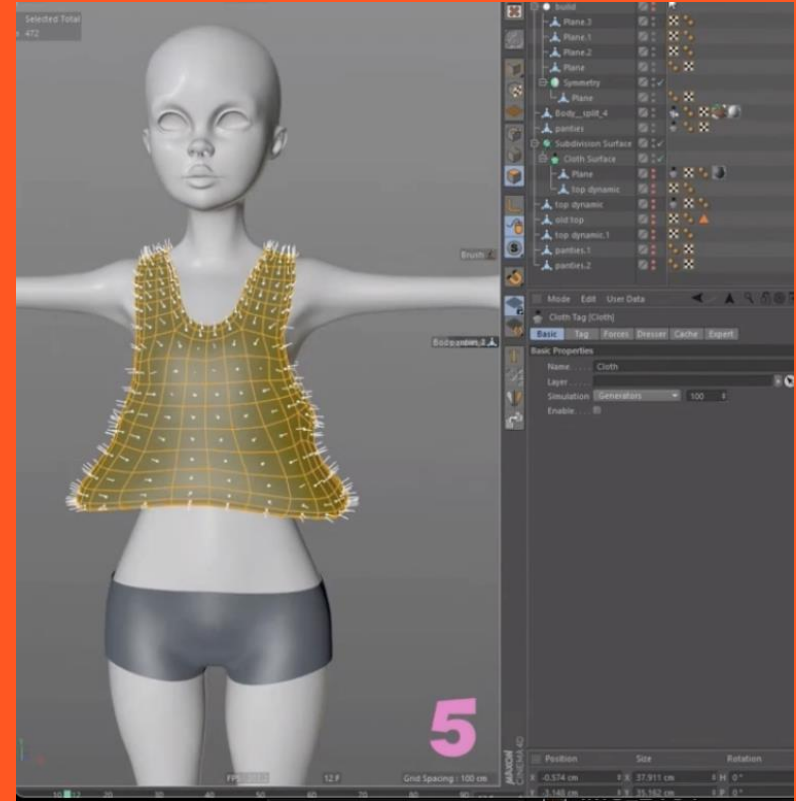


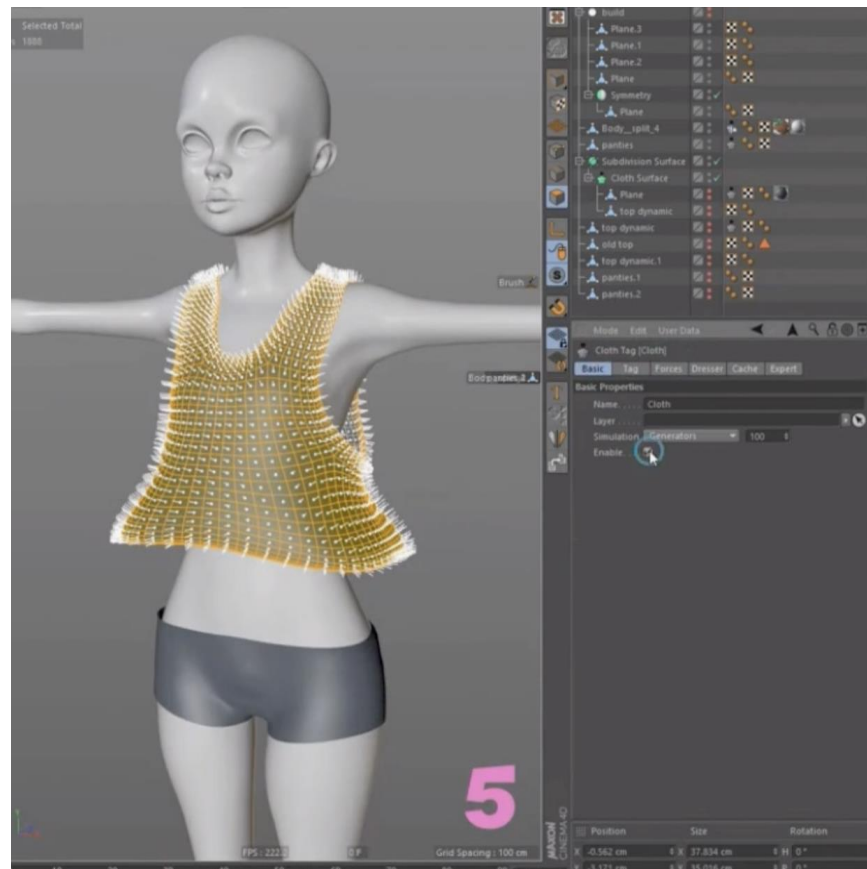
# CURLY HAIR SIMPLE SIMULATION

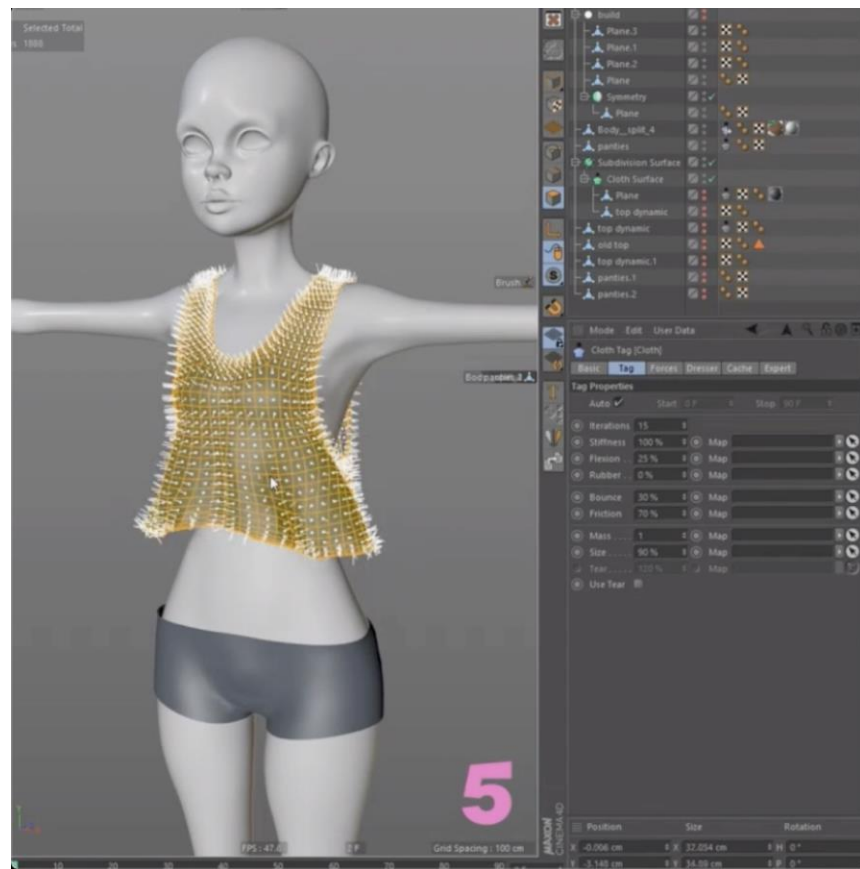
- Hooke's Law:  $F = -kx$ 
  - $F$ = Spring force  $k$ = Spring constant  $x$ = Spring displacement (stretch or compression)
  - Find the displacement to calculate the positions of the vertices in the simulation in real time
    - Assuming the environment generates a net force on the particles (gravity), use these factors to calculate the acceleration and velocity of each particle. The net force includes the force the surrounding springs would contribute.
    - Velocity equation:  $v = \Delta x / \Delta t$ 
      - This would yield the displacement of the particle from its starting position and now the computer knows where to display this object. This is too taxing for a human to calculate- hence the need for simulations

# CLOTHING

- Articles of clothing are made up of vertices
- When running the simulation each vertex is responding to its corresponding equations
- Here we see:
  - Gravity
  - Relationships to other vertices (now a web rather than a string)
  - Collision with human model
  - Initially assigned position in 3D space



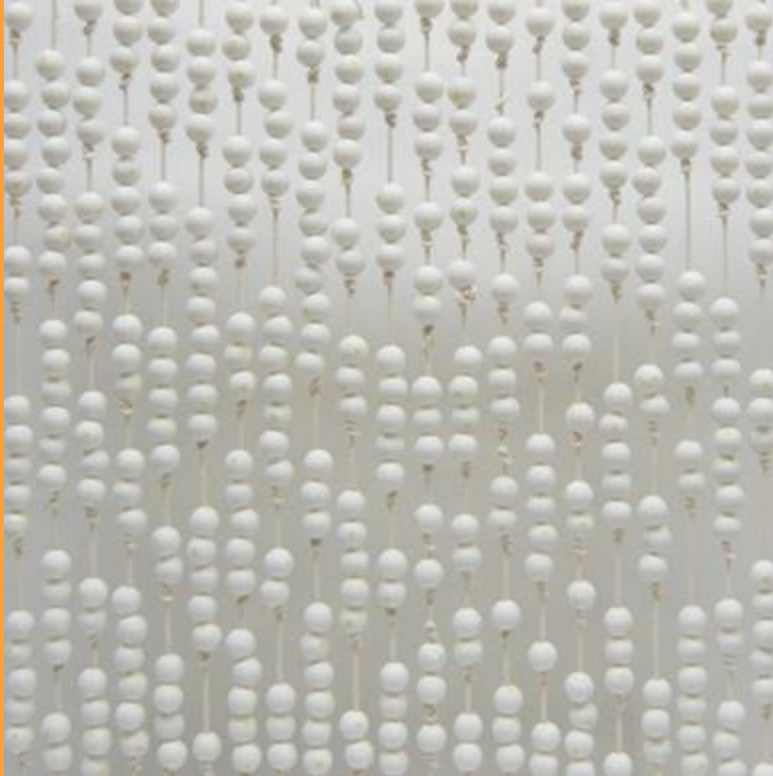








# SIMULATING CURTAIN WITH PARTICLES



- Things to consider:
  - Collision
  - Mass of each bead
  - Springs connecting the beads
- Things to ignore:
  - Webs or meshes of clothing
    - For the purpose of the simulation, I am returning back to individual chains rather than a web of vertices

# GOALS

- Create believable simulated motion
  - In the examples previously shown, attributes have been assigned to the particles and objects for believability. I will not be creating these attributes, only attempting to apply the equations to them.
  - Attributes could be:
    - Color, glow, scale, opacity, shadows, etc.
- Interactivity + Collision
  - Not only simulate the curtain with the relationships between the particles, have the curtain react realistically when something moves through it.

# ADDITIONAL VARIABLES

- Collision

- Newton's Third Law of Motion

- Upon a collision between two of these objects, the force acted on one vertex, will be matched in the opposite direction. Therefore, their motion paths will be reversed.
    - Need to take this into account when calculating their position if a bead encounters another bead AND/OR the character.

BUT these objects don't always collide at a perfect perpendicular.

# ADDITIONAL VARIABLES

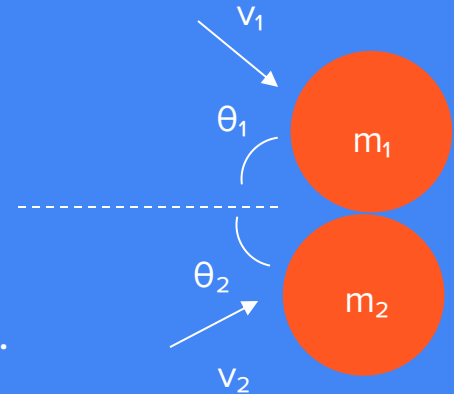
- Collision

- $M_1 v_1 = m_1 v'_1 \cdot \cos(\theta_1) + m_2 v'_2 \cdot \cos(\theta_2)$

- Where:

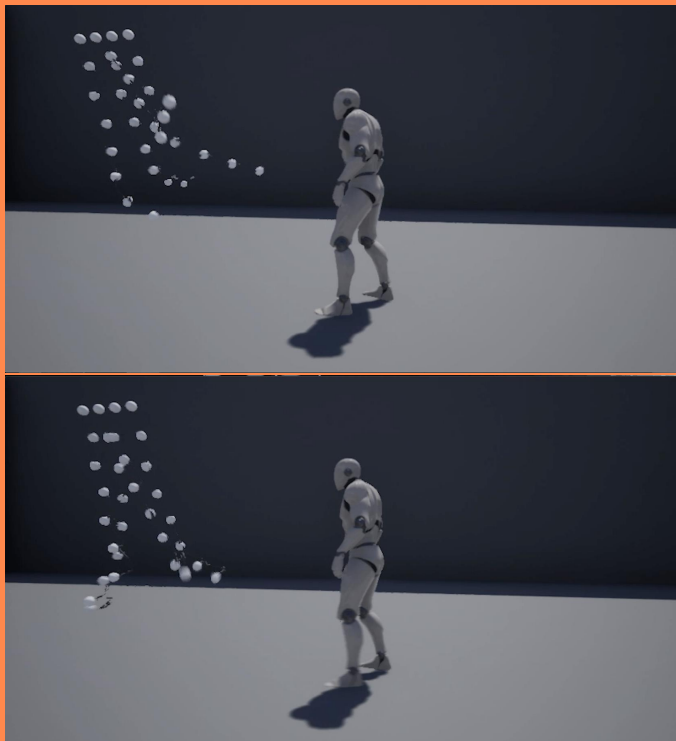
- $m_1, m_2$  = masses of the objects
    - $v_1, v_2$  = initial velocities
    - $v'_1, v'_2$  = subsequent velocities
    - $\theta_1, \theta_2$  = angles adjacent to the relative perpendicular axis

- The program has the initial positions, mass and velocities for the objects. This is used to calculate the resulting forces angle, and velocity.

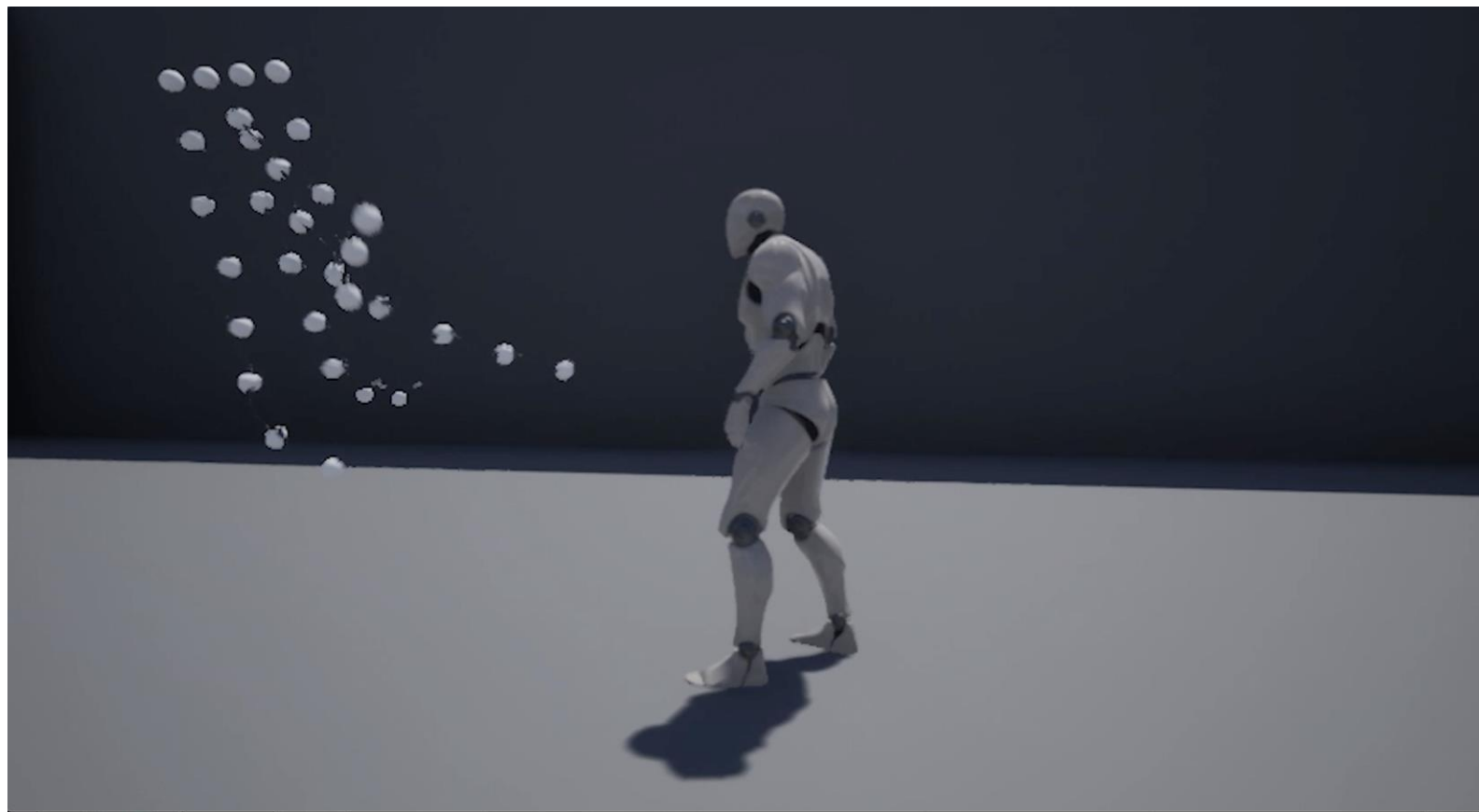


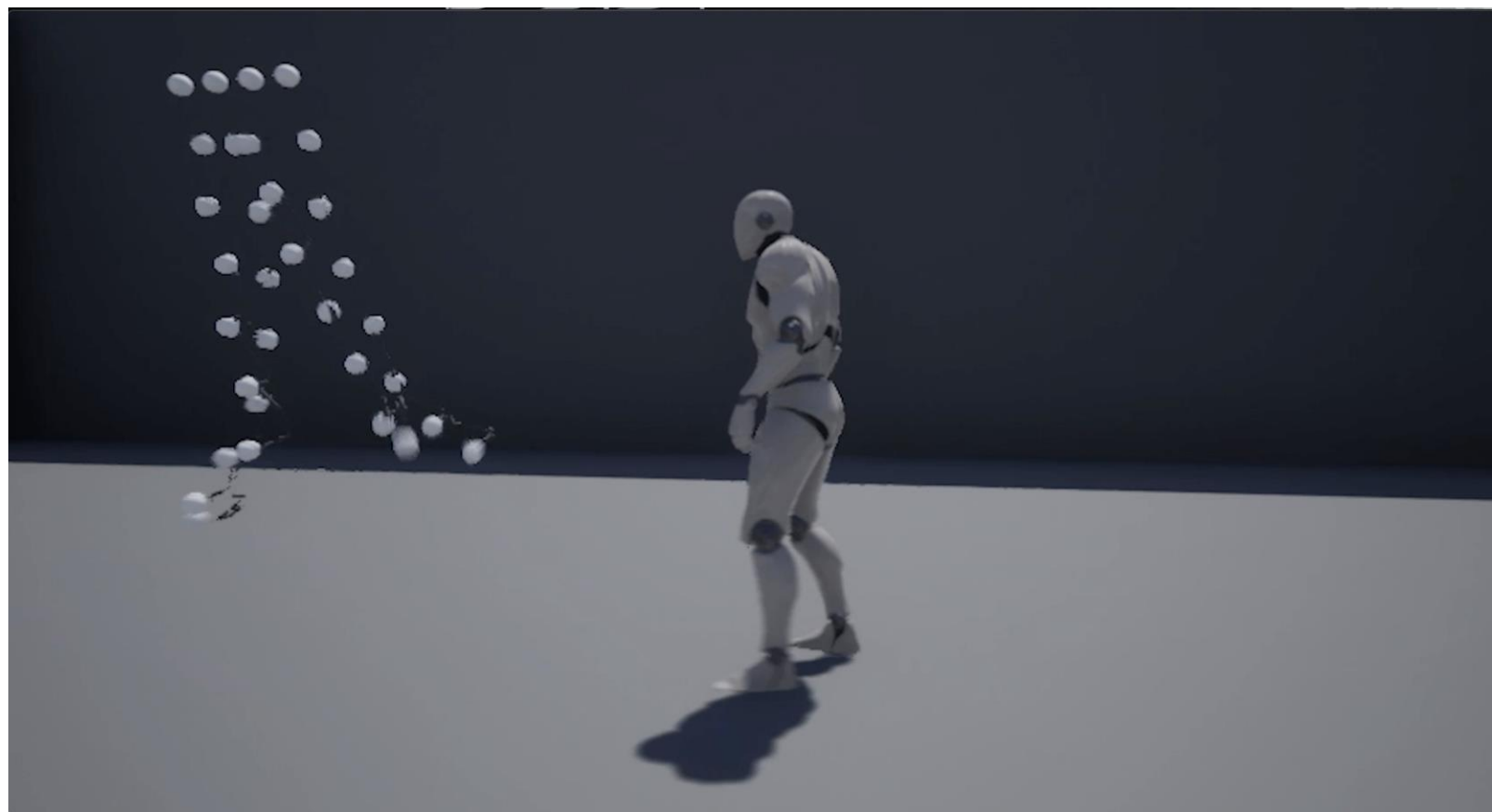


# CURTAIN SIMULATION

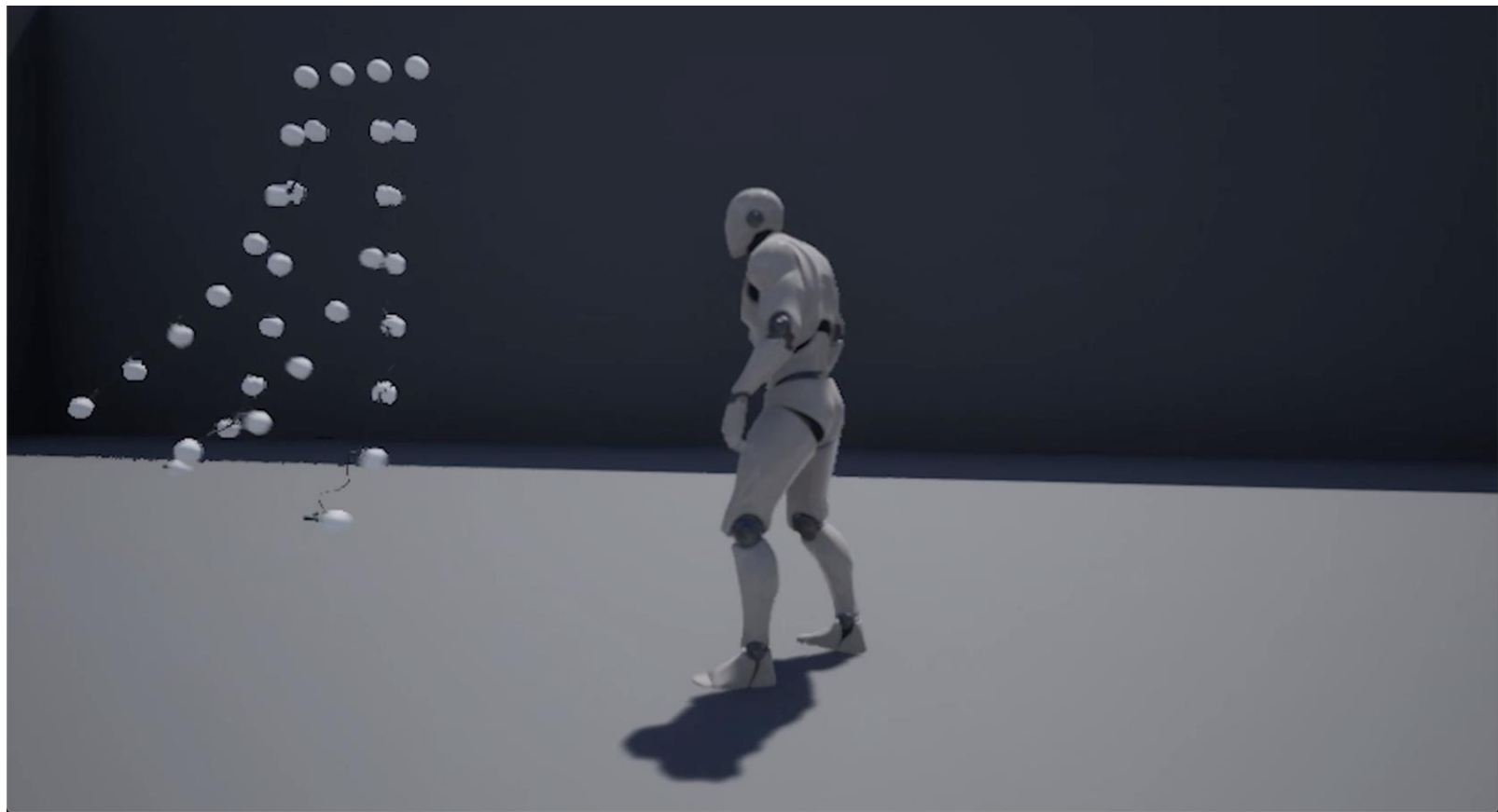


- Reacting well to each other and simulating gravity
- The bead curtain became less believable when the character encountered it. The collision was interacting with too many vertices and overwhelming the simulation.

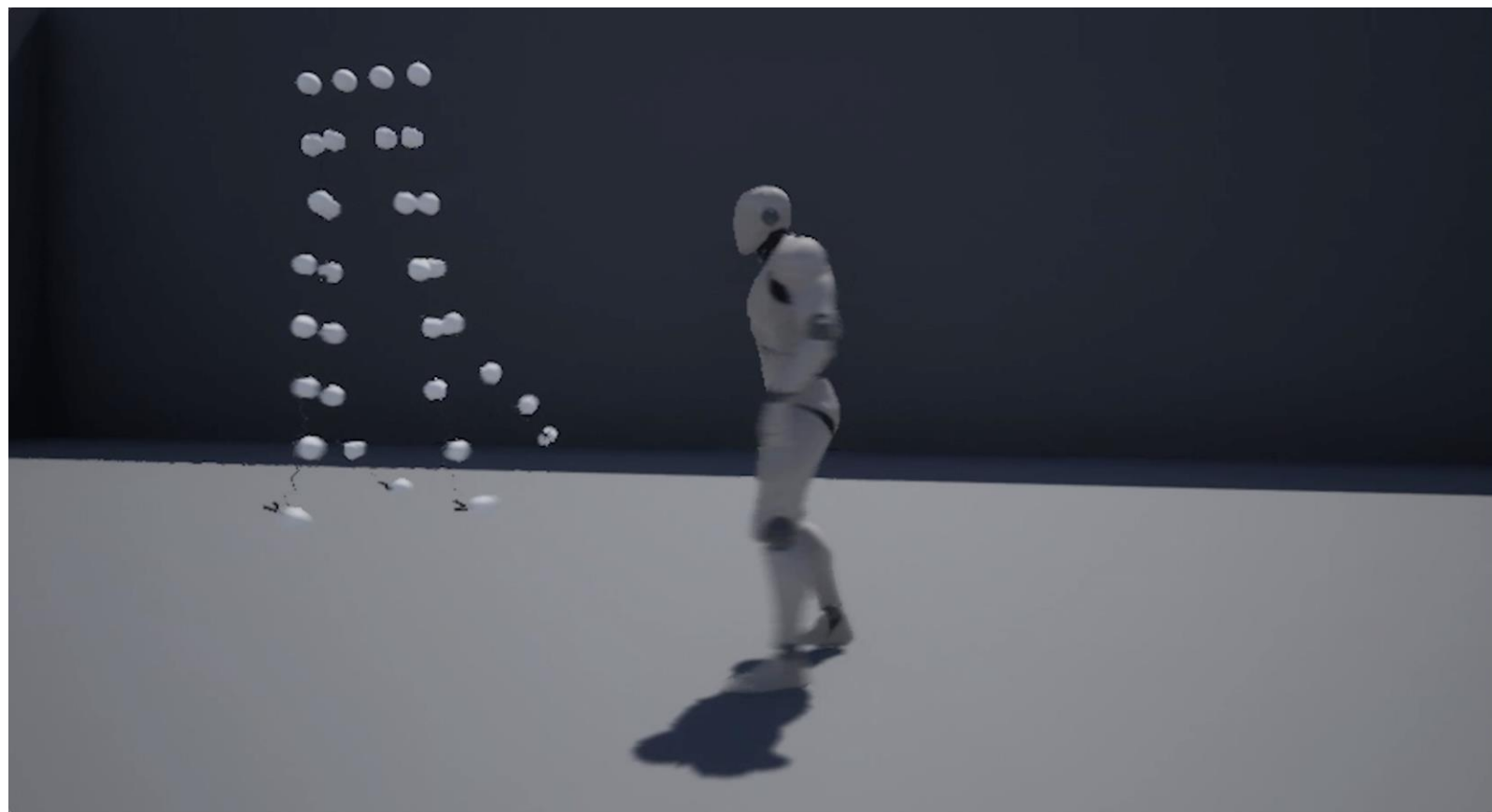






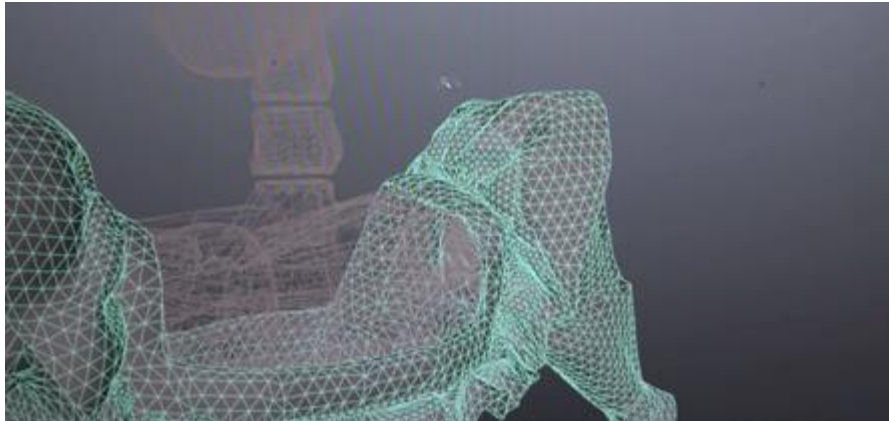






# HOW TO EXPAND THIS

- Use vertices as subdivisions of planes to create a volume or web- known as a mesh or topology
- Then instead of a bead curtain, it would act as a hanging sheet of cloth - move as one



# SOURCES

- <https://www.khanacademy.org/computing/pixar>
- [https://threejs.org/examples/#webgl\\_animation\\_cloth](https://threejs.org/examples/#webgl_animation_cloth)
- <https://www.britannica.com/science/Hookes-law>
- <https://www.britannica.com/science/Newtons-laws-of-motion>